# **Supplementary Material: Optimal Algorithms for Lipschitz Bandits with Heavy-tailed Rewards**

## A. Proof of Theorem 1

**Theorem 1** Assume (1) and (2) hold. For sufficiently large T such that

$$\log T = \frac{5}{8} (4)^{-\frac{1}{\epsilon}}$$

the regret of SDTM with parameter r > 0 satisfies

$$\mathbb{E}[R(T)] = 2rT + (4 T)^{\frac{1}{1+\epsilon}} (16N_c(r) \log T)^{\frac{\epsilon}{1+\epsilon}}$$

where  $N_c(r)$  is the r-covering number of the arm set X.

**Proof.** Let  $x_* \supseteq \arg\max_{x \in \mathcal{X}} (x)$  be an optimal arm. By the definition of the oracle, there must exist  $k \supseteq [K]$  such that  $x_* \supseteq X_k$  and hence  $D(x_*; \bar{x}_k)$   $\supseteq T$ . Since the expected reward function is Lipschitz, we have

$$(x_*) \qquad (\bar{x}_k) \qquad D(x_*, \bar{x}_k) \qquad 2r: \tag{17}$$

On the other hand, let  $\bar{x}_* \ 2\arg\max_{x_i,i\in[K]} \ (\bar{x}_i)$  be an optimal skeleton arm. By theoretical guarantees of UCB policies used with the truncated mean estimator (Bubeck et al. 2013, Proposition 1), the expected difference between the cumulative reward of the pulled arms and that of the optimal skeleton arm  $X_*$  can be upper bounded as follows

$$\mathbb{E} \left( \overline{X}_{*} \right) = \left( X_{t} \right) \left( X_{t} \right) = \left( 4 \ T \right)^{\frac{1}{1+\epsilon}} \left( 16 K \log T \right)^{\frac{\epsilon}{1+\epsilon}} : \tag{18}$$

where we use the fact that  $(\bar{x}_k)$   $(\bar{x}_*)$ .

# B. Proof of Corollary 2

Corollary 2 We have

$$\underset{r=2^{-i}:i\in\mathbb{N},r\geq r_0}{\times} \frac{N_z(r)}{r^{1/\epsilon}} \quad O \quad r_0^{-(d_z+1/\epsilon)}$$

and thus

$$R(T) \quad O \quad \inf_{\substack{r_0 \in (0,1) \\ \emptyset}} r_0 T + \log T \quad r_0^{-(d_z + 1/\epsilon)}$$

where  $d_z$  is the zooming dimension of  $(X; \cdot)$ , defined in (5).

**Proof.** We have

$$\underset{r=2^{-i}:i\in\mathbb{N},r\geq r_0}{\times} \frac{N_z(r)}{r^{1/\epsilon}} \qquad \underset{i\in\mathbb{N}:2^{-i}\geq r_0}{\times} 2^{id_z+i/\epsilon}Z \qquad \underset{i=0}{\overset{\lfloor\log_2\frac{1}{r_0}\rfloor}{\sim}} 2^{id_z+i/\epsilon}Z \qquad \underset{0}{\overset{Z\log_2\frac{1}{r_0}+1}{\sim}} 2^{id_z+i/\epsilon}Z\,\mathrm{d}i \qquad \underbrace{(2=r_0)^{d_z+1/\epsilon}Z}_{\log\left(2^{d_z+1/\epsilon}\right)}$$

where Z is the zooming constant of (X; D).

## C. Proof of Theorem 3

**Theorem 3** Assume (2) and (12) hold. With probability at least 1 2, the regret of ADMM satisfies

$$R(T) \quad \inf_{r_0 \in (0,1)} r_0 T + \\ 68(102^-)^{\frac{1}{\epsilon}} \log \left( e^{1/8} T^2 = \right) \times \frac{N_z(r)}{r^{1/\epsilon}}$$

where  $\bar{}$  is defined in (13) and  $N_z(r)$  is the r-zooming number of (X; ). Furthermore, by the first inequality in Corollary 2 we have

$$R(T)$$
  $\Theta$   $T^{\frac{d_z\epsilon+1}{d_z\epsilon+\epsilon+1}}$ 

where  $d_z$  is the zooming dimension of  $(X; \cdot)$ , defined in (5).

**Proof.** We use the same notations as in the proof of Theorem 2 and propose the following lemmas, which are counterparts of Lemmas 1, 2, 3, and 4 respectively. For brevity, we only prove Lemmas 5 and 6, and the proofs of Lemmas 7 and 8 can be done in the same way as in appendices G and H respectively.

**Lemma 5** Let R be the set comprised of all rounds in which Step 21 of Algorithm 4 is executed. Then, with probability at least 1 2, for all rounds t 2R and all active arms  $x 2A_t$ , we have

$$jb_t(x)$$
  $(x)j$   $r_{t+1}(x)$ :

**Proof.** Fix  $t \ge R$  and  $x \ge A_t$ . By Lemma 2 in Bubeck et al. (2013), with probability at least  $1 - \frac{2\delta}{T^2}$  we have

$$jb_{t}(x) \qquad (x)j \quad (12)^{\frac{1}{1+\epsilon}} \quad \frac{16\log\left(e^{1/8}T^{2}\right)}{n_{t}(x)} \quad \frac{\frac{\epsilon}{1+\epsilon}}{n_{t}(x)} \quad (12^{-})^{\frac{1}{1+\epsilon}} \quad \frac{16\log\left(e^{1/8}T^{2}\right)}{n_{t}(x)} \quad \frac{\frac{\epsilon}{1+\epsilon}}{n_{t}(x)} = r_{t+1}(x)$$

Taking the union bound over  $x \ge A_t$  and  $t \ge R$  and noticing  $jA_tj = T$ ;  $8t \ge R$ , we conclude the proof.

**Lemma 6** With probability at least 1 2, for all rounds  $t \in T$  and all active arms  $x \in A_t$ , we have

$$\Delta(x) = 3^{\mathcal{O}} \bar{2} r_{t+1}(x)$$
:

**Proof.** Fix  $t \ge |T|$ . For each active arm  $x \ge A_t$ , there exist three different scenarios as follows.

(i) x is pulled by Step 4 or Step 10 of Algorithm 4 in round t. In this scenario, on one hand, we have

$$n_t(x)$$
 16 log  $(e^{1/8}T^2 = ) + 1$ 

and hence

$$r_{t+1}(x) = (12^{-})^{\frac{1}{1+\epsilon}} \quad \frac{16\log\left(e^{1/8}T^{2}=\right)}{n_{t}(x)} \quad \frac{\frac{\epsilon}{1+\epsilon}}{(12^{-})^{\frac{1}{1+\epsilon}}} \quad \frac{16\log\left(e^{1/8}T^{2}=\right)}{16\log\left(e^{1/8}T^{2}=\right) + 1} \quad \frac{\frac{\epsilon}{1+\epsilon}}{(12^{-})^{\frac{1}{1+\epsilon}}} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{\frac{\epsilon}{1+\epsilon}}{36} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{35}{36} \quad \frac{1}{3} = \frac$$

where the second inequality follows from the definition of  $\bar{t}$  in (13) and the following fact:  $16\log\left(e^{1/8}T^2=\right)>35$  for T>1 and  $2\left(0;1=2\right)$ . On the other hand, let  $X_*=2\arg\max_{x\in\mathcal{X}}(x)$  be an optimal arm. We have  $\Delta(x)=(x_*)$  (x)  $D(x_*;x)$  1. Thus, we obtain  $3\frac{1}{2}T_{t+1}(x)$   $\Delta(x)$ .

(ii) x is pulled by Step 12 of Algorithm 4 in round t. In this case, we have t = 1.2 R and the arm selection rule implies

$$b_{t-1}(x) + 2r_t(x)$$
  $b_{t-1}(x') + 2r_t(x')$ ;  $8x' \ge A_t$ : (19)

Note that  $A_t = A_{t-1}$ . By Lemma 5, we get

(x) 
$$b_{t-1}(x) r_t(x)$$
;  $b_{t-1}(x') (x') r_t(x')$ ;  $8x' 2A_t$ : (20)

Combining (19) and (20), we obtain

$$(x) + 3r_t(x)$$
  $(x') + r_t(x')$ ;  $8x' \ 2A_t$ : (21)

Note that the execution of Step 12 implies  $X = \int_{x \in \mathcal{A}_t} B(x; r_t(x))$ . Thus, for the optimal arm  $x_*$  there must exist an active arm  $\bar{x}_* \supseteq A_t$  such that

$$D(\mathbf{X}_*; \bar{\mathbf{X}}_*) \quad r_t(\bar{\mathbf{X}}_*)$$

which, together with the Lipschitz property of , indicates

$$(X_*)$$
  $(\bar{X}_*) + r_t(\bar{X}_*)$ :

Combining the above inequality and (21) with substitution  $x' = \bar{x}_{*}$ , we obtain

$$(x) + 3r_t(x)$$
  $(x_*)$ :

On the other hand, we have

$$\frac{r_{t+1}(x)}{r_t(x)} = \frac{n_{t-1}(x)}{n_t(x)} = \frac{\frac{\epsilon}{1+\epsilon}}{n_{t-1}(x)} = \frac{n_{t-1}(x)}{n_{t-1}(x)+1} = \frac{1}{\frac{\epsilon}{1+\epsilon}}$$

Therefore, we get  $3^{\bigcirc} \overline{2} r_{t+1}(x) = 3r_t(x) = \Delta(x)$ :

(iii) x is not played in round t. In this scenario, let s be the last round in which x is pulled. Then, we have  $r_{t+1}(x) = r_{s+1}(x)$  and the proof reduces to (i) or (ii).

**Lemma 7** With probability at least 1 2, for all i = 0; 1; 2; ...;

$$j\bar{A}_T(i)j$$
  $N_z(2^{-i})$ :

**Lemma 8** With probability at least 1 - 2, for all i = 0; 1; 2; ...;

$$\times n_T(x)\Delta(x) \quad 2^{\frac{i+1}{\epsilon}} \quad (51^-)^{\frac{1}{\epsilon}} \quad 68\log(e^{1/8}T^2 = )N_z(2^{-i}):$$

$$x \in \mathcal{A}_T(i)$$

The remaining proof is the same as that of Theorem 2 and is omitted here.

## D. Proof of Theorem 4

**Theorem 4** Fix an arm set X with diameter 1 and a parameter of moment 2(0;1]. Define  $=\frac{2^{1/\epsilon} \cdot \epsilon}{\log 2}$  and

$$R_c(T) = \inf_{r_0 \in (0,1)} r_0 T + \log T \times \prod_{r=2^{-i}: i \in \mathbb{N}, r > r_0} \frac{N_c(r)}{r^{1/\epsilon}}$$

where  $N_c(r)$  is the r-covering number of X. Then, for any T>2 and any positive number  $R-R_c(T)$ , there exists a set I of problem instances on X such that

(i) for each problem instance I 2 I, define

$$R_z(T) = \inf_{r_0 \in (0,1)} \quad r_0 T + \log T \underset{r=2^{-i}: i \in \mathbb{N}, r \ge r_0}{\times} \frac{N_z(r)}{r^{1/\epsilon}}$$

in which  $N_z(r)$  is the r-zooming number of I. We have  $R_z(T) = 3R = (8 \log T)$ :

(ii) for any algorithm A, there exists at least one problem instance  $I \ 2 \ I$  on which the expected regret of A satisfies  $\mathbb{E}[R(T)] \quad R=(2560 \ \log T)$ :

**Proof.** Our proof is inspired by Slivkins (2014) and makes use of the needle-in-the-haystack technique, which is firstly proposed by Auer et al. (2002b) for analyzing multi-armed bandits and then extended to Lipschitz bandits by Kleinberg et al. (2013).

**Step 1 (Constructing instance set** /) We begin with the following lemma.

Lemma 9 Define

$$R'_c(T) = \inf_{r_0 \in (0,1)} r_0 T + \log T \frac{N_c(r_0)}{r_0^{1/\epsilon}}$$
:

Then for any T > 2,  $R_c(T)$   $R'_c(T)$ .

**Proof.** Since  $N_c(r)$  is non-increasing with r, we have

$$R_{c}(T) = \inf_{r_{0} \in (0,1)} r_{0}T + \log T \times \inf_{r_{0} = 2^{-i}: i \in \mathbb{N}, r \geq r_{0}} \frac{N_{c}(r)}{r^{1/\epsilon}} \qquad \inf_{r_{0} \in (0,1)} r_{0}T + \log T N_{c}(r_{0}) \times \inf_{r_{0} = 2^{-i}: i \in \mathbb{N}, r \geq r_{0}} r^{-\frac{1}{\epsilon}}$$

in which the last term can be upper bounded as follows

$$\underset{r=2^{-i}: i \in \mathbb{N}, r \geq r_0}{\times} r^{-\frac{1}{\epsilon}} = \underset{i=0}{\overset{\lfloor \log_2 \frac{1}{r_0} \rfloor}{r_0}} \overset{Z_{\log_2 \frac{1}{r_0} + 1}}{0} 2^{\frac{i}{\epsilon}} \ di = \frac{(2 = r_0)^{1/\epsilon}}{\log{(2^{1/\epsilon})}} \frac{1}{\log{2} \ r_0^{1/\epsilon}}$$

Recalling  $=\frac{2^{1/\epsilon} \cdot \epsilon}{\log 2} > 1$ , we conclude the proof.

Fix T>2 and  $R=R_c(T)$ . Let  $r=\frac{R}{2\kappa T(1+\log T)}$  and  $N=\max(2;bTr^{1+1/\epsilon}c)$ . Based on Lemma 9, we can bound r and N as follows.

**Lemma 10** We say a subset S = X is an r-packing of X if the distance between any two points in S is at least r, i.e.,  $\inf_{u,v \in S} D(u;v) = r$ . Let  $N_p(r)$  denote the r-packing number of X, defined as the maximal number of points in an r-packing of X:

$$N_p(r) = \max f j S j : S$$
 is an r-packing of  $X g$ :

We have

$$r < 1=2$$
 and  $N N_n(r)$ :

**Proof.** Define function  $f(r) = \frac{N_c(r)}{r^{1+1/\epsilon}}$ . Since f(1) = 1,  $\lim_{r \to 0} f(r) = +7$ , and f(r) is decreasing on (0;1), there must exist  $\mathfrak{b} \ \mathcal{D}(0;1)$  such that  $f(\mathfrak{b}) = T$  f( $\mathfrak{b}$ =2). From the first inequality, we obtain

$$R \quad R_c(T) \qquad R_c'(T) \qquad \text{b}T + \frac{N_c(\mathfrak{b})}{\mathfrak{p}^{1/\epsilon}} \log T \qquad \text{b} \quad T(1 + \log T)$$

which implies  $r = \frac{\widehat{r}\kappa T(1+\log T)}{2\kappa T(1+\log T)} = \frac{\widehat{r}}{2} < \frac{1}{2}$ . From the second inequality, we have

$$\mathcal{T}r^{1+1/\epsilon} \qquad \mathcal{T}\left(\mathbb{b}=2\right)^{1+1/\epsilon} \qquad \frac{\mathcal{N}_c(\mathbb{b}=2)}{\left(\mathbb{b}=2\right)^{1+1/\epsilon}} \left(\mathbb{b}=2\right)^{1+1/\epsilon} \qquad \mathcal{N}_c(r):$$

We conclude the proof by the fact that  $N_c(r) = N_p(r)$  (Kleinberg et al., 2013) and  $2 = N_p(r)$ 

The above lemma ensures that we can find a set of arms  $U = fu_1, \ldots, u_N g$  X such that  $\inf_{x,y \in \mathcal{U}} D(x,y)$  r. Based on U, we construct a set of problem instances  $I = fI_1, \ldots, I_N g$ . Let us fix  $i \geq [N]$  and describe the construction of  $I_i$ : the expected reward function  $I_i$  is defined as

$$\begin{cases}
\frac{8}{8}; & x = u_i \\
i(x) = \frac{3r}{4}; & x = u_j; j \ 2 [N] \text{ and } j \notin i
\end{cases}$$

$$\underset{i}{\approx} \max(\frac{r}{2}; \max_{u \in \mathcal{U}} i(u) \quad D(x; u)); \text{ otherwise}$$
(22)

and the reward distributions are defined by

$$\Pr(y|x) = p_i(y|x) = \begin{cases} (x)r^{1/\epsilon}; & y = r^{-1/\epsilon} \\ 1 & i(x)r^{1/\epsilon}; & y = 0 \end{cases}$$
 (23)

One can show that for  $i = 1, 2, \dots, N$ , is Lipschitz and the (1 + )-th moment of  $p_i$  is upper bounded by 7=8.

**Step 2 (Proving i)** Let / be a problem instance in / . Recall the definition of -optimal region:  $X_{\rho} = fx \ 2 \ X$ : =2 <  $\Delta(x)$  g. It is clear that for 3r=4, we have  $X_{\rho} = \varnothing$  and thus  $N_z(\ ) = 0$ . It follows that

$$R_{z}(T) = \inf_{r_{0} \in (0,1)} r_{0}T + \log T \times \frac{X}{\rho = 2^{-i} : i \in \mathbb{N}, \rho \geq r_{0}} \frac{N_{z}()}{1/\epsilon} \frac{3}{4}rT + \log T \times \frac{N_{z}()}{\rho = 2^{-i} : i \in \mathbb{N}, \rho \geq \frac{3}{4}r} \frac{N_{z}()}{1/\epsilon} \frac{3R}{8 \log T}$$

where the last inequality is due to  $r = \frac{R}{2\kappa T(1+\log T)}$ .

**Step 3 (Proving ii)** Following the framework of Kleinberg et al. (2013), we first introduce an auxiliary problem instance  $I_0$  in which the expected reward function  $I_0$  is defined as

$$_{0}(x) = \begin{pmatrix} \frac{3r}{4}; & x = u_{j}; j \geq [N] \\ \max(\frac{r}{2}; \max_{u \in \mathcal{U}} _{0}(u) & D(x; u)); & \text{otherwise} \end{pmatrix}$$

and the reward distributions are defined by

$$\Pr(y|x) = p_0(y|x) = \begin{cases} (x)r^{1/\epsilon}; & y = r^{-1/\epsilon} \\ 1 & o(x)r^{1/\epsilon}; & y = 0 \end{cases}$$

The advantage of this construction of  $I_0$  is that the extent to which any other problem instance  $I_i 2 /$  deviates from  $I_0$  can be controlled as follows. Let  $S_i = B(u_i)$ 

#### E. Proof of Lemma 1

**Lemma 1** With probability at least 1 2, for all rounds t 2 [T] and all active arms  $x \in A_t$ , we have

$$jb_t(x)$$
  $(x)j$   $r_{t+1}(x)$ :

**Proof.** Fix  $t \supseteq [T]$  and  $x \supseteq A_t$ . By Lemma 1 in Bubeck et al. (2013), with probability at least  $1 = \frac{2\delta}{T^2}$  the following holds

$$j b_t(x) \qquad (x) j \quad 4^{-\frac{1}{1+\epsilon}} \quad \frac{\log \left(T^2 = \right)}{n_t(x)} \quad \frac{\epsilon}{1+\epsilon} \quad 4^{-\frac{1}{1+\epsilon}} \quad \frac{\log \left(T^2 = \right)}{n_t(x)} \quad \frac{\epsilon}{1+\epsilon} = r_{t+1}(x):$$

Taking the union bound over  $x \ge A_t$  and  $t = 1, 2, \dots, T$  and noticing  $jA_t/T$ ;  $8t \ge [T]$ , we conclude the proof.

#### F. Proof of Lemma 2

**Lemma 2** With probability at least 1 2, for all rounds t 2[T] and all active arms  $x \in A_t$ , we have

$$\Delta(x) \quad 3^{\mathcal{D}} \overline{2} r_{t+1}(x)$$
:

**Proof.** Fix  $t \ge [T]$ . For each active arm  $x \ge A_t$ , there exist three different scenarios as follows.

(i) x is pulled by Step 7 of Algorithm 2 in round t. In this scenario, on one hand, we have  $n_t(x) = 1$  and

$$r_{t+1}(x) = 4^{-\frac{1}{1+\epsilon}} \quad \frac{\log(T^{2} = 1)}{n_{t}(x)} \quad \frac{\epsilon}{1+\epsilon} \quad 4^{-\frac{1}{1+\epsilon}} \quad \frac{1}{3^{\frac{1}{2}}}$$

where we use the fact that  $\log (T^2 = ) - \log 4 - 1$  for T > 1. On the other hand, let  $x_* 2 \arg \max_{x \in \mathcal{X}} - (x)$  be an optimal arm. We have

$$\Delta(x) = (x_*) \qquad (x) \qquad D(x_*; x) \qquad 1$$

where the first inequality holds since is Lipschitz, and the second inequality is due to the assumption in (2). Thus, we obtain  $3\sqrt[3]{2}r_{t+1}(x) = \Delta(x)$ .

(ii) x is pulled by Step 9 of Algorithm 2 in round t. In this case, we have t-2 and  $n_{t-1}(x)-1$  and the arm selection rule implies

$$b_{t-1}(x) + 2r_t(x)$$
  $b_{t-1}(x') + 2r_t(x')$ ;  $8x' \ge A_t$ : (25)

Note that  $A_t = A_{t-1}$ . By Lemma 1, we get

(x) 
$$b_{t-1}(x) r_t(x)$$
;  $b_{t-1}(x') (x') r_t(x')$ ;  $8x' 2A_t$ : (26)

Combining (25) and (26), we obtain

$$(x) + 3r_t(x)$$
  $(x') + r_t(x')$ ;  $8x' \ 2A_t$ : (27)

Note that the execution of Step 9 implies  $X = \int_{x \in \mathcal{A}_t} B(x; r_t(x))$ . Thus, for the optimal arm  $x_*$  there must exist an active arm  $\bar{x}_* \supseteq A_t$  such that

$$D(\mathbf{X}_*; \bar{\mathbf{X}}_*) \qquad r_t(\bar{\mathbf{X}}_*)$$

which, together with the Lipschitz property of , indicates

$$(X_*)$$
  $(\bar{X}_*) + r_t(\bar{X}_*)$ :

Combining the above inequality and (27) with substitution  $x' = \bar{x}_*$ , we obtain

$$(\mathbf{x}) + 3\mathbf{r}_t(\mathbf{x})$$
  $(\mathbf{x}_*)$ :

On the other hand, we have

$$\frac{r_{t+1}(x)}{r_t(x)} = \frac{n_{t-1}(x)}{n_t(x)} \stackrel{\frac{\epsilon}{1+\epsilon}}{=} \frac{n_{t-1}(x)}{n_{t-1}(x)+1} \stackrel{\frac{\epsilon}{1+\epsilon}}{=} \frac{1}{2}.$$

Therefore, we get  $3^{\mathcal{D}} \overline{2} r_{t+1}(x) = 3r_t(x) = \Delta(x)$ :

(iii) x is not played in round t. In this scenario, let s be the last round in which x is pulled. Then, we have  $r_{t+1}(x) = r_{s+1}(x)$  and the proof reduces to (i) or (ii).

## G. Proof of Lemma 3

**Lemma 3** With probability at least 1 2, for all  $i \geq \mathbb{N}$ ,

$$j\bar{A}_T(i)j$$
  $N_z(2^{-i})$ :

**Proof.** By the definition of the r-zooming number, for i=0; 1; 2;  $\dots$ , the set  $\bar{A}_T(i)$  can be covered by not more than  $N_z(2^{-i})$  balls of radius at most  $\frac{1}{18\times 2^i}$ . In the following, we show that each of these balls contains at most one arm from  $\bar{A}_T(i)$ . In fact, suppose that there exist two arms u;  $v \ge \bar{A}_T(i)$  falling into the same ball. On one hand, we have

$$D(u;v) = \frac{1}{9 - 2^i}. \tag{28}$$

On the other hand, without loss of generality, we assume arm u is added into the active arm set  $A_T$  before arm v. Let t be the time when arm v is added into  $A_T$ . The execution of Algorithm 2 ensures t-2 and

$$D(u;v) > r_t(u). \tag{29}$$

By Lemma 2, we have

$$r_t(u) = r_{t+1}(u)$$
  $\frac{\Delta(u)}{3} > \frac{1}{6} = \frac{1}{2} = 2^i$   $> \frac{1}{9 - 2^i}$ 

which, together with (28) and (29), leads to a contradiction. Thus,  $j\bar{A}_T(i)j = N_z(2^{-i})$ .

#### H. Proof of Lemma 4

**Lemma 4** With probability at least 1 2, for all  $i 2 \mathbb{N}$ ,

$$\bigwedge_{x \in \mathcal{A}_T(i)} n_T(x) \Delta(x) \quad 2^{\frac{i+1}{\epsilon}} \quad 17^{\frac{\epsilon+1}{\epsilon} - \frac{1}{\epsilon}} \log (T^2 = ) \mathcal{N}_z(2^{-i}) :$$

**Proof.** For any arm  $x \supseteq \bar{A}_T(i)$ , by Lemma 2 we have

$$\Delta(x) = 3^{\mathcal{O}} \overline{2} r_{T+1}(x) = 17^{-\frac{1}{1+\epsilon}} = \frac{\log(T^2 = 1)}{n_T(x)} = \frac{\epsilon}{1+\epsilon}$$
:

Rearranging the above inequality, we obtain

$$n_T(x)\Delta(x) = 17^{\frac{\epsilon+1}{\epsilon}-\frac{1}{\epsilon}}\log\left(T^2\right) = \Delta(x)^{-\frac{1}{\epsilon}} = 2^{\frac{i+1}{\epsilon}} = 17^{\frac{\epsilon+1}{\epsilon}-\frac{1}{\epsilon}}\log\left(T^2\right)$$

where the second inequality is due to  $\Delta(x) > 2^{-(i+1)}$ : We finish the proof by applying Lemma 3.

#### I. Proof of Lemma 11

**Lemma 11** The Kullback–Leibler divergence from  $Q_k$  to  $Q_0$  satisfies

$$KL(Q_0; Q_k)$$
 39=200:

**Proof.** We first bound the KL divergence from  $p_0$  to  $p_k$ :

$$KL(p_0; p_k) = \ _0(x) r^{1/\epsilon} \log \ \frac{_0(x) r^{1/\epsilon}}{_k(x) r^{1/\epsilon}} \ + (1 \ _0(x) r^{1/\epsilon}) \log \ \frac{1 \ _0(x) r^{1/\epsilon}}{1 \ _k(x) r^{1/\epsilon}} \ :$$

In the following, we consider two different scenarios, i.e.,  $x \ge X$   $S_k$  and  $x \ge S_k$ . (i)  $x \ge X$   $S_k$ . By (24), we have  $S_k = S_k = S_k$ .

$$KL(p_0; p_k) = 0: (30)$$

(ii) 
$$x \ge S_k$$
. By (24), we have  $_0(x)$   $_k(x)$   $_0(x) + r=8$  which implies

$$KL(p_0; p_k) = {}_{0}(x)r^{1/\epsilon} \log \frac{{}_{0}(x)r^{1/\epsilon}}{{}_{0}(x)r^{1/\epsilon}} + (1 {}_{0}(x)r^{1/\epsilon}) \log \frac{1}{1} \frac{{}_{0}(x)r^{1/\epsilon}}{{}_{0}(x)r^{1/\epsilon}} \frac{r^{1+1/\epsilon} = 8}{r^{1+1/\epsilon} = 8}$$

$$(1 {}_{0}(x)r^{1/\epsilon}) \frac{r^{1+1/\epsilon} = 8}{1} \frac{r^{1+1/\epsilon} = 8}{0} = (1 {}_{0}(x)r^{1/\epsilon}) \frac{r^{1+1/\epsilon} = 8}{r^{1+1/\epsilon} = 8} + r^{1+1/\epsilon} = 8$$

$$= \frac{r^{1+1/\epsilon}}{8} + \frac{r^{1+1/\epsilon} = 8}{1} \frac{r^{1+1/\epsilon} = 8}{0} \frac{r^{1+1/\epsilon} = 8}{1}$$

$$= \frac{r^{1+1/\epsilon}}{8} + \frac{r^{1+1/\epsilon} = 8}{1} \frac{r^{2}}{7r^{1+1/\epsilon} = 8}$$

$$= \frac{r^{1+1/\epsilon}}{8} + \frac{r^{1+1/\epsilon} = 8}{4r^{1+1/\epsilon}} \frac{r^{2}}{7r^{1+1/\epsilon} = 8}$$

$$= \frac{13}{100} r^{1+1/\epsilon}$$
(31)

where the second inequality follows from the well-known inequality:  $\log a = a + 1$ ; 8a > 0, the third inequality is due to  $_0(x) \ 2 \ [r=2; 3r=4]$ , and the last inequality holds since  $4r^{1+1/\epsilon} - 4 + (1=2)^{1+1/\epsilon} - 4 + (1=2)^2 = 1$ .

We continue the proof of Lemma 11 as follows. Denote by KL(::j) the conditional KL divergence also known as conditional relative entropy (Cover & Thomas, 1991; Kleinberg et al., 2013). For t = 1; :::; T, we have

$$KL(Q_0^t; Q_k^t j h^{t-1}) = X \atop h^t \in t Q_0^t(h^t) \log \frac{Q_0^t(h^t j h^{t-1})}{Q_k^t(h^t j h^{t-1})} 
= X \atop h^t \in t Q_0^t(h^t) \log \frac{Q_0^t(x_t j h^{t-1})}{Q_k^t(x_t j h^{t-1})} \frac{Q_0^t(y_t j x_t; h^{t-1})}{Q_k^t(y_t j x_t; h^{t-1})} 
= X \atop h^t \in t Q_0^t(h^t) \log \frac{Q_0^t(y_t j x_t; h^{t-1})}{Q_k^t(y_t j x_t; h^{t-1})}$$

where the first equality is the definition of conditional KL divergence and the last equality is due to the fact that the distribution of  $x_t$  given  $h^{t-1}$  depends only on the algorithm A. We proceed as follows

$$\begin{split} \mathcal{K}L(\mathcal{O}_{0}^{t};\mathcal{O}_{k}^{t}\,j\,h^{t-1}) &= \begin{array}{c} & \times \\ & & \\ & & \\ & & \times \end{array} \mathcal{O}_{0}^{t}(h^{t})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{k}^{t}(y_{t}\,j\,x_{t};h^{t-1})} \\ &= \begin{array}{c} & \times \\ & \times \\ & & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{k}^{t}(y_{t}\,j\,x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{k}^{t}(y_{t}\,j\,x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{k}^{t}(y_{t}\,j\,x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{k}^{t}(y_{t}\,j\,x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{0}^{t}(x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})\log & \frac{\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1})}{\mathcal{O}_{0}^{t}(x_{t};h^{t-1})} & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) \\ &= \begin{array}{c} & \times \\ & \times \end{array} \mathcal{O}_{0}^{t}(y_{t}\,j\,x_{t};h^{t-1}) & \mathrm{d}\,\mathcal{O}_{0}$$

Finally, by the chain rule of KL divergence we have

$$KL(Q_0; Q_k) = KL(Q_0^T; Q_k^T) = \bigvee_{t=1}^{\mathcal{K}} KL(Q_0^t; Q_k^t j h^{t-1}) \qquad \bigvee_{t=1}^{\mathcal{K}} \frac{13}{100} r^{1+1/\epsilon} Q_0^t (x_t \ 2 \ S_k) = \frac{13}{100} r^{1+1/\epsilon} \mathbb{E}_{Q_0}[Z_k] : \mathcal{L}(Q_0^t; Q_k^t j h^{t-1}) = \bigvee_{t=1}^{\mathcal{K}} KL(Q_0^t; Q_0^t j$$

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where we use the convention that  $h^0=\varnothing$ . Recalling  $\mathbb{E}_{Q_0}[Z_k]$  T=N and  $N=\max(2;bTr^{1+1/\epsilon}c)$ , we obtain

$$\mathbb{E}_{Q_0}[Z_k] \quad \frac{3}{2} r^{-(1+1/\epsilon)}$$

which completes the proof.